

Investigation of the Richtmyer-Meshkov instability with double perturbation interface in nonuniform flows

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A nonuniform SF₆ gas flow initial condition has been actualized in the context of shock tube experiment for the Richtmyer-Meshkov instability study. Two kinds of amplitude have been used to design the membrane supports which initially materialize the gaseous interface. The visualizations of air/SF₆ sinusoidal interfaces and shock wave propagations in the nonuniform field were obtained by Schlieren photography. Experiments are in very good agreement with simulations for the air/SF₆ case, but due to the initial nonuniform effects, Sadot model and Zhang-Sohn theory are far beyond the experimental and calculation results.

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Richtmyer-Meshkov (RM) instability has been studied in many theoretical, numerical, and experimental works. Pure hydrodynamics RM experiments are mainly realized in shock tubes. In the case of the RM instability, the interface between the two gases is always unstable due to the vorticity production linked with the misalignment between the pressure and the density gradients when the shock wave passes through the interface. Afterwards, the interface perturbations grow and develop into spikes and bubbles which can evolve into mushroom structures. The small perturbations initially presented on the interface will grow first linearly, then at later time, nonlinear development of the perturbations will take place and subsequent transition to turbulence will occur. The shock wave interaction with instable interface has gained much attention over the past decades due to its importance in physics systems such as inertial confinement fusion (ICF) and astrophysical phenomena [1,2]. As we all know, different initial conditions have a major effect on the development and evolution of the interface instability throughout the process. Numerous papers [1,3–6] stress the uncertainty about the initial conditions of the interface and it can induce more uncertainty in the use of experimental data to test numerical schemes. In all known horizontal or vertical shock tube experiments, the initial interfacial conditions are rarely accurately measured [1,7] but often backward estimated. Recently, a novel method to produce an accurately profiled initial interface has been developed to study the instability of a gaseous interface impulsively accelerated in a shock tube [8]. As a consequence, experiments that are more suited to both theoretical and numerical studies are needed.

In those papers published, whether experimental or numerical simulation studies interface instability, the initial flows are almost seen as a uniform flow field. However, we are well aware that the initial flow state could produce to a certain extent effect on development and evolution of the interface instability. Thus, the aim of the present paper is to investigate the influence of nonuniform flow initial conditions on the interface instability. The experiments are performed in the LSD's horizontal shock tube which is 5 m long and 20 × 10 cm² rectangular cross section. It is coupled with a high-speed Schlieren photography (the time between two

consecutive frames is 100 μs) which allows a two-dimensional (2D) visualization of the interface. We chose the air and SF₆ gases and hope the SF₆ gas constitutes the initial nonuniform flow field. The incident shock wave mach number is 1.27 in air. The air shock waves through the air and SF₆ interface and enters into the SF₆ gas nonuniform flow field. Meanwhile, we set two different kinds of initial perturbations with the same wavelength and different amplitude on the interface. The purpose is to observe the impact of the nonuniform flow field on the development and evolution of perturbation. How to achieve nonuniform flow field and determine the initial-state parameters of nonuniform flow field are the first to be considered before the experiment, as it may directly impact on interface instability. First of all, for obtaining an initial nonuniform SF₆ gas flow field, the simplest and natural way is that two holes with diameter Φ=10 mm are opened at the bottom and top of shock tube, respectively, and the SF₆ gas is injected into the shock tube from the lower hole and left from the upper hole. In order to maintain a constant pressure of SF₆ gas flow field, the gas flow speed is very slow, about 0.417 cm/s. When the SF₆ gas flow speed stabilizes more than 20 min later, we begin to experiment. As the gas diffusion effect will make a larger proportion of SF₆ gas in the lower part of shock tube, it can form naturally the initial nonuniform flow field. The state of SF₆ gas before experiment is that the concentration is larger with higher density at the lower part of shock tube and the concentration is smaller with lower density at the upper part of shock tube. The pressure of initial nonuniform flow field is 1 atm and the initial spatial distribution of density is difficult to be measured in vertical direction and not known. In the experiment, we mainly measured the SF₆ gas concentrations at the entrance (bottom) and exit (top); they are 0.95 and 0.71, respectively. Therefore, we need to determine the initial distribution of density in the nonuniform flow field with the help of numerical simulation and experimental results for reproducing the whole experimental process and understanding the impact of nonuniform flow field on the development and evolution of perturbations. This work has an important significance on the setting of initial conditions for experimental study of interface instability, analysis of experimental phe-

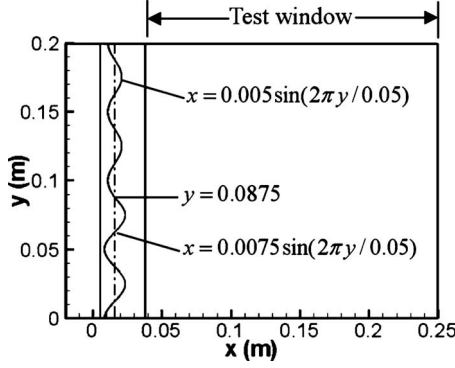


FIG. 1. Initial structure diagram in the shock tube.

nomenon, and results. Air/SF₆ interface for dual-mode sinusoidal perturbation is that the wavelength is 0.05 m, wave number $\omega = 2\pi/\lambda$, and the amplitudes are $A_1 = 5.0 \times 10^{-3}$ and $A_2 = 7.5 \times 10^{-3}$ m, respectively. The perturbation function is $x = A_1 \sin(\omega y)$ when $0.0 \leq y < 0.0875$ m and $x = A_2 \sin(\omega y)$ when $0.0875 < y \leq 0.2$ m. The size of Schlieren photography observation test window is 0.212×0.2 m² in the x - y plane in our experiment. The initial structure diagram is shown in Fig. 1, the initial shock front is located at $x = 5.56 \times 10^{-3}$ m, the equilibrium position of perturbation is at $x = 0.016$ m, and the range of observation test window is $[0.038-0.25]$ m, corresponding to experiment in the x direction. For avoiding the influence of the membrane, a thin nitrocellulosic membrane (about ~ 1 μ m thickness) is constructed. Table I summarizes the properties of air and SF₆ gas in the present experiment at 1 atm and 20 °C.

This paper presents the numerical simulation investigation of the experiment. Based on the multiviscous-fluid piecewise parabolic method [9], the Vreman [10] subgrid eddy viscosity model is employed to the Navier-Stokes equations. Two-dimensional and three-dimensional (3D) large eddy simulation codes MVFT2D (2D multiviscous flow and turbulent) and MVFT3D for the multiviscosity fluid and turbulence resulting from the fluid interface instability are developed. The flow equations are given by

$$\begin{aligned} \frac{\partial \bar{\rho}}{\partial t} + \frac{\partial \bar{\rho} \bar{u}_j}{\partial x_j} &= 0, \\ \frac{\partial \bar{\rho} \bar{u}_i}{\partial t} + \frac{\partial \bar{\rho} \bar{u}_j \bar{u}_i}{\partial x_j} + \frac{\partial \bar{p}}{\partial x_i} &= \frac{\partial (\bar{\sigma}_{ij} + \tau_{ij})}{\partial x_j}, \\ \frac{\partial \bar{\rho} \bar{E}}{\partial t} + \frac{\partial (\bar{\rho} \bar{u}_j \bar{E} + \bar{p} \bar{u}_j)}{\partial x_j} &= -\frac{\partial (\bar{q}_j + Q_j)}{\partial x_j} + \frac{\partial [\bar{u}_i (\bar{\sigma}_{ij} + \tau_{ij})]}{\partial x_j}, \\ \frac{\partial \bar{Y}^{(s)}}{\partial t} + \bar{u}_j \frac{\partial \bar{Y}^{(s)}}{\partial x_j} &= \frac{\partial}{\partial x_j} \left(\bar{D} \frac{\partial \bar{Y}^{(s)}}{\partial x_j} \right), \quad s = 1, 2, \dots, N-1, \end{aligned} \quad (1)$$

where $\bar{\sigma}_{ij} = \mu_l [\partial \bar{u}_i / \partial x_j + \partial \bar{u}_j / \partial x_i - 2/3 \delta_{ij} (\partial \bar{u}_k / \partial x_k)]$ is the viscous stress tensor, $\tau_{ij} = \rho (u_i u_j - \bar{u}_i \bar{u}_j)$ is the subgrid scale (SGS) stress tensor, $\bar{q}_j + Q_j$ is the energy flux of unit time and space, $\bar{q}_j = -\lambda_l \partial \bar{T} / \partial x_j$, $Q_j = -\lambda_l \partial \bar{T} / \partial x_j$, $\lambda_l = \mu_l c_p / p_{r,l}$,

TABLE I. Properties of air and SF₆ gas.

Gas	Density (g/cm ³)	Specific heat ratio	Kinematic viscosity (10 ⁻⁶ m ² /s)	Prandtl number	Diffusion coefficient in air (cm ² /s)
Air	1.29	1.40	15.7	0.71	0.204
SF ₆	5.34	1.09	2.47	0.90	0.097

$\lambda_l = \mu_l c_p / p_{r,l}$, $\bar{D} = \bar{D}_l + D_t$, and $S_{c,t} = \mu_l / D_l \bar{\rho}$. μ_l is the fluid viscosity, \bar{T} is the temperature, λ_l is the efficient heat-transfer coefficient, c_p is the specific heat of fluid, $p_{r,l}$ is the Prandtl number, \bar{D}_l is the diffusion coefficient, and D_t is the turbulent diffusion coefficient. Operator-splitting technique is used to decompose the physical problems, described by Eq. (1), into three subprocesses, i.e., the computations of inviscid flux, viscous flux, and heat flux. Equation (1) can be decomposed into two equations as follows:

$$\begin{aligned} \frac{\partial \bar{\rho}}{\partial t} + \frac{\partial \bar{\rho} \bar{u}_j}{\partial x_j} &= 0, \\ \frac{\partial \bar{\rho} \bar{u}_i}{\partial t} + \frac{\partial \bar{\rho} \bar{u}_j \bar{u}_i}{\partial x_j} + \frac{\partial \bar{p}}{\partial x_i} &= 0, \\ \frac{\partial \bar{\rho} \bar{E}}{\partial t} + \frac{\partial (\bar{\rho} \bar{u}_j \bar{E} + \bar{p} \bar{u}_j)}{\partial x_j} &= 0, \\ \frac{\partial \bar{Y}^{(s)}}{\partial t} + \bar{u}_j \frac{\partial \bar{Y}^{(s)}}{\partial x_j} &= 0, \quad s = 1, 2, \dots, N-1, \\ \frac{\partial \bar{\rho}}{\partial t} &= 0, \\ \frac{\partial \bar{\rho} \bar{u}_i}{\partial t} &= \frac{\partial (\bar{\sigma}_{ij} + \tau_{ij})}{\partial x_j}, \\ \frac{\partial \bar{\rho} \bar{E}}{\partial t} &= -\frac{\partial (\bar{q}_j + Q_j)}{\partial x_j} + \frac{\partial [\bar{u}_i (\bar{\sigma}_{ij} + \tau_{ij})]}{\partial x_j}, \\ \frac{\partial \bar{Y}^{(s)}}{\partial t} &= \frac{\partial}{\partial x_j} \left(\bar{D} \frac{\partial \bar{Y}^{(s)}}{\partial x_j} \right), \quad s = 1, 2, \dots, N-1. \end{aligned} \quad (2)$$

For the inviscid flux, the 3D problem can be simplified into three one-dimensional (1D) problems by dimension-splitting technique. For the 1D problem, we apply two-step Lagrange-Remap algorithm to solve the equations and a time step calculation can be divided into four steps: (i) the piecewise parabolic interpolation of physical quantities, (ii) solving Riemann problems approximately, (iii) marching of Lagrange equations, and (iv) remapping the physical quantities to stationary Euler meshes. More information can be obtained in the author's literature [11]. For the viscous flux and heat flux, they are calculated by utilizing second-order

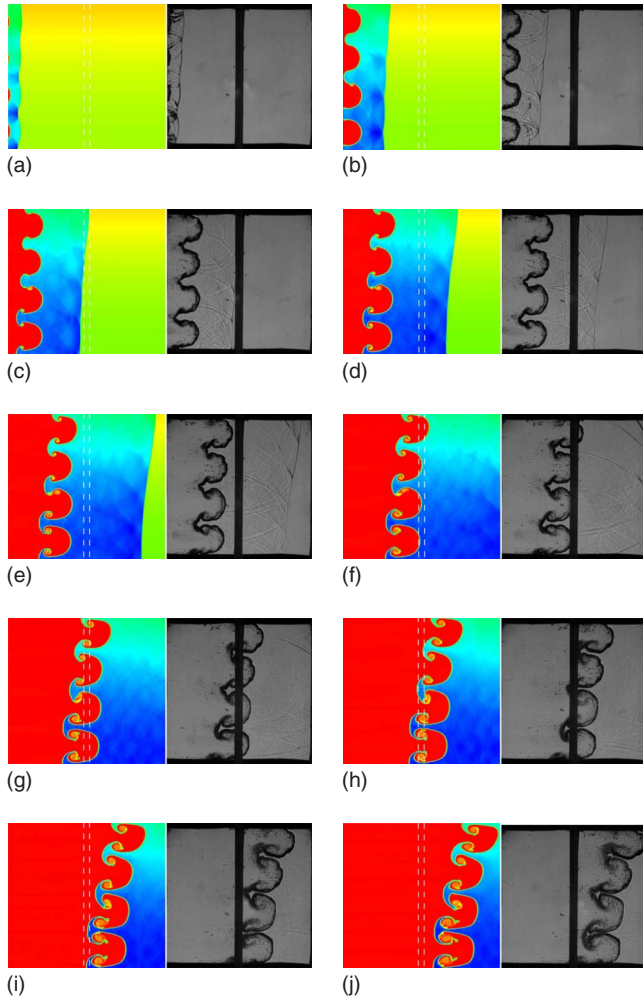


FIG. 2. (Color online) Schlieren photography pictures and numerical simulation results by MVFT2D at a certain time (the sizes of the pictures are ones of the test window $[0.038 \text{ m}, 0.25 \text{ m}] \times [0.0 \text{ m}, 0.2 \text{ m}]$).

spatial center difference and two-step Runge-Kutta time marching. The Vreman SGS turbulent model is applied [10]

$$\mu_t = C_V \rho \sqrt{\frac{\Pi_\beta}{\bar{\alpha}_{ij} \bar{\alpha}_{ij}}}, \quad (4)$$

with $\bar{\alpha}_{ij} = \partial \bar{u}_j / \partial x_i$, $\Pi_\beta = \beta_{11} \beta_{22} - \beta_{12} + \beta_{11} \beta_{33} - \beta_{13} + \beta_{22} \beta_{33} - \beta_{23}$, and $\beta_{ij} = \sum_{m=1}^3 \Delta_m^2 \bar{\alpha}_{mi} \bar{\alpha}_{mj}$. The model constant C_V is related to the Smagorinsky constant C_S by $C_V \approx 2.5 C_S^2$ ($C_V = 0.07$ in this paper).

For the initial nonuniform SF_6 gas flow field, numerical simulation is used to approximately describe the dissipative transition layer [12]. In the dissipative transition layer, SF_6 gas density is calculated by Gaussian function

$$\rho(y) = \rho_{\text{SF}_6} e^{-[(y - y_c)^2 / \delta^2]}, \quad (5)$$

where $y_c = 0$ and $\delta = 0.3729 \text{ m}$. The calculating region is $[-0.02 \text{ m}, 0.25 \text{ m}] \times [0.0 \text{ m}, 0.2 \text{ m}]$ and it is discretized into 540×400 grids. Sample images from the experiment and the corresponding numerical results are shown in Fig. 2. These images have been chosen because they can illustrate

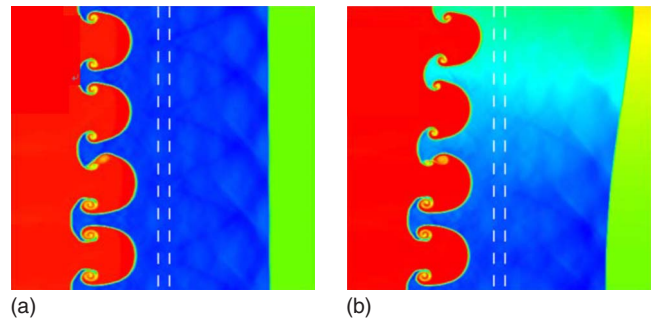


FIG. 3. (Color online) Difference of interface shape, location, and shock front at $t = 1.0 \text{ ms}$ between the initial uniform and nonuniform flows (the sizes of the pictures are the same as Fig. 2). (a) Initial uniform flow. (b) Initial nonuniform flow.

some salient features of the experiment. By using the Schlieren photography, we obtained two-dimensional flow field Schlieren diagram from $t = 0.2$ to 2.0 ms at intervals of 0.2 ms and they are shown in the right side of Figs. 2(a)–2(j) (the black vertical strip in the each figure is the transparent glass support structure). From the experimental results in Figs. 2(a)–2(j), we can see that, due to the nonuniform flow field of SF_6 gas, the density distribution changes from high to low along the shock tube vertically, and this results in the propagating velocity of shock wave in the upper part of shock tube faster than in the bottom of shock tube, and forms an oblique shock wave front. The calculating images of MVFT2D are shown in the left side of Figs. 2(a)–2(j) (the white vertical dashed lines denote the supporting frames). Figure 2 shows that the calculated developments of the interface shape, location, and oblique shock wave propagating features are consistent with the experimental results. The main difference between calculation and experiment is that the experimental Schlieren shock tube map is the integral result along the thickness direction, but the calculated result is only a two-dimensional section. If we do not take into account the nonuniformity of SF_6 gas in the calculation, then the calculated results of the interface shape, location, and oblique shock propagating characteristics will be quite different from experimental results. Figure 3 shows two kinds of calculated results and experimental images at 1.0 ms ; the difference is clear and will be discussed in the following part. Turbulence is a highly complex three-dimensional unsteady state, with a rotating irregular flow. The physical parameters of turbulence such as speed, pressure, temperature, and so on change randomly over time and space and can be regarded as random distribution. The turbulent flow can also be superimposed by a variety of different scales vortex. The

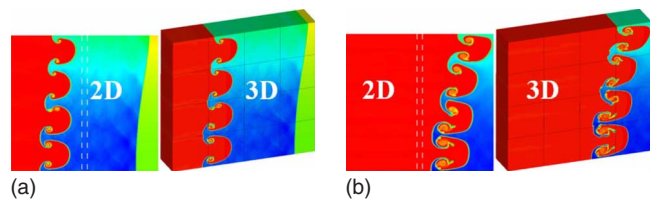


FIG. 4. (Color online) Comparisons of the MVFT2D and MVFT3D results at two times (the sizes of the pictures are same as Fig. 2).

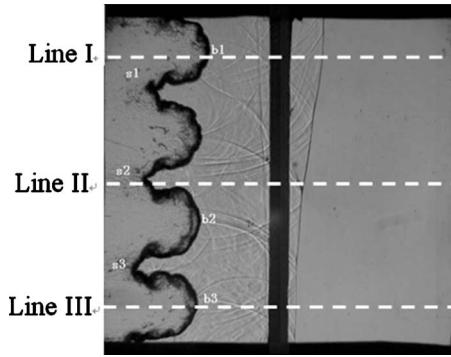


FIG. 5. Bubble and spike locations in test window as well as three shock front line positions.

above calculation is only in two-dimensional x - y plane shock tube and did not consider the dissipation in z direction. Two-dimensional calculation results may be stronger, so we also carried out three-dimensional numerical simulation. The thickness of three-dimensional model in z direction is 5 cm and the total calculating grids are $540 \times 400 \times 100$. Figure 4 shows the comparison between two- and three-dimensional calculating results. It can be seen that both the calculating shape and location of the interface are almost exactly same and the differences of physics characteristics in the flow are very small. So we think the RM instability in this experiment has not yet fully developed to the turbulent state.

The degree of influence can be described by the two measurable properties in our shock tube experiments. The first is to accurately catch the two kinds of initial sinusoidal perturbations with same wavelength and different amplitude of the gaseous interface and the second is to exactly capture the front of shock wave in the nonuniform flow field. These two properties become the keys in our experiments. Figure 5 shows the locations of bubble and spike, and three shock front line observations. In Fig. 5, B1-S1 corresponds to the position of peak and trough of the initial small perturbation and B3-S3 corresponds to the position of peak and trough of

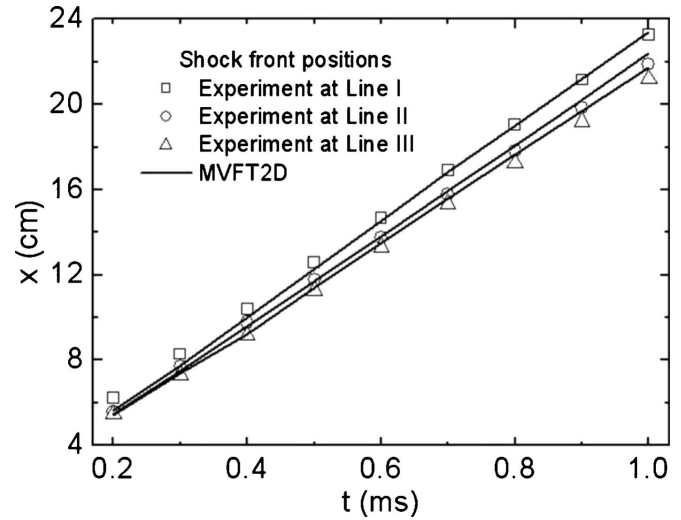


FIG. 6. Shock front locations of the experiment and calculated results on the three test lines at different time.

the initial large perturbation, while the positions of three observed shock fronts are line I 17.26 cm, line II 9.82 cm, and line III 2.78 cm, respectively. Figure 6 shows the location of three test lines at different times, including experimental and calculated results. When the time is greater than 1.0 ms, the shock front has spread out the testing window and the figure did not give comparative data. From the comparison of the results in Fig. 6, we can see that the difference between calculated and experimental shock-front positions along the line I is about 5% before 0.4 ms, afterwards the difference is almost same. Along the line II and line III, shock-front locations of calculation and experiment are almost perfectly matching in early times, but the difference is about 3% after 0.8 ms. This difference may be due to the initial calculation of density distribution for nonuniform flow field using Gaussian function; it is just an approximation of the real situation. This approximation describes the flow field characteristics and a smaller difference with the practice is ac-

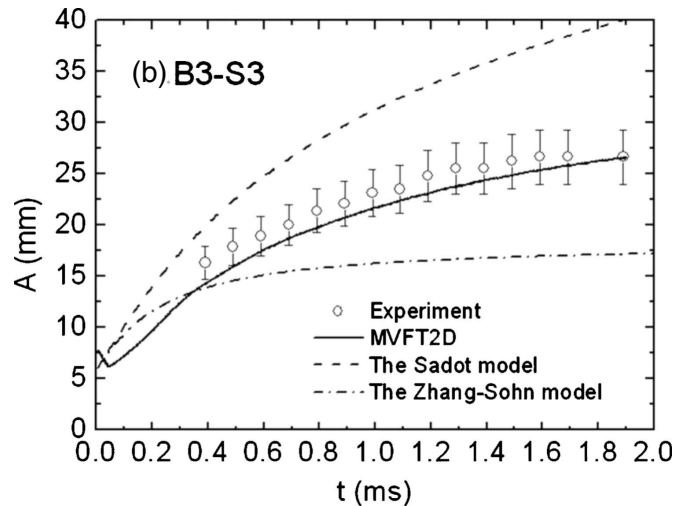
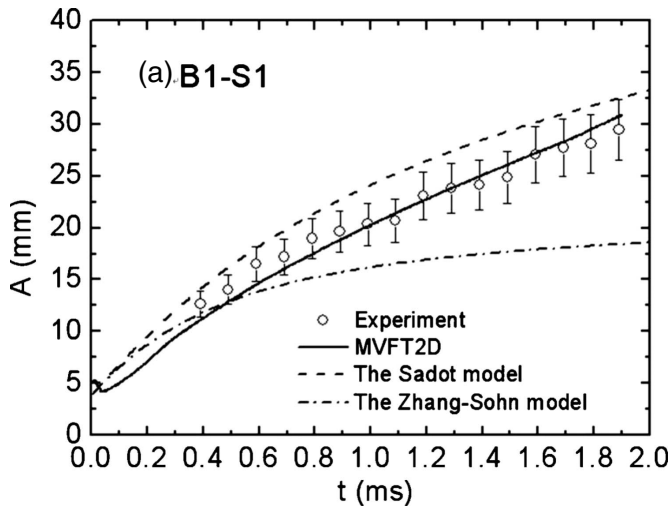


FIG. 7. Perturbation amplitudes history of the experiment, numerical computing, and comparison to the Sadot model and Zhang-Sohn theory, B1-S1 corresponds to the small perturbation amplitude, and B3-S3 corresponds to the large one (error bars of this visual measurement are equal to $\pm 10\%$).

ceptable. Figure 7 shows the comparison between the B1-S1 and B3-S3 perturbation amplitude histories of experiment, numerical computing, Sadot model, and the theory of Zhang-Sohn, in which the bar denotes the experimental error about $\pm 10\%$. From Fig. 7, we can see that, for the two different kinds of perturbation, the differences between numerical and experimental values were within 10%, while the results of Sadot model for B1-S1 amplitude are closer to experimental and computational results. The results of Sadot model for B3-S3, as well as Zhang-Sohn theory for the both are far beyond the experimental and computational results. In order to analyze the effect of initial uniform and nonuniform flow fields on the interface instability, Fig. 8 shows the calculated history of two kinds of perturbation amplitude for initial uniform and nonuniform flow fields. As it can be seen, there are two kinds of differences: for uniform flow field, when $t > 0$, the perturbation amplitude of B3-S3 is always greater than the perturbation amplitude of B1-S1. But for nonuniform flow field, at $0 < t \leq 1.3$ ms, the perturbation amplitude of B3-S3 is greater than the perturbation amplitude of B1-S1, while at $t > 1.3$ ms the opposite results appeared; the perturbation amplitude of B1-S1 is greater than the perturbation amplitude of B3-S3. This interesting phenomenon shows that for the RM instability, in addition to the initial conditions of perturbation interface, the flow field nonuniformity also has a significant effect on the interface instability.

In summary, an initial condition of nonuniform SF_6 gas flow has been actualized in the context of shock tube experiment for the RM instability study. By using Schlieren photography, the air/ SF_6 sinusoidal interfaces and shock wave propagations in the nonuniform field were obtained. By the numerical simulation tool, we determined the initial density distribution of nonuniform flow field and reproduced the

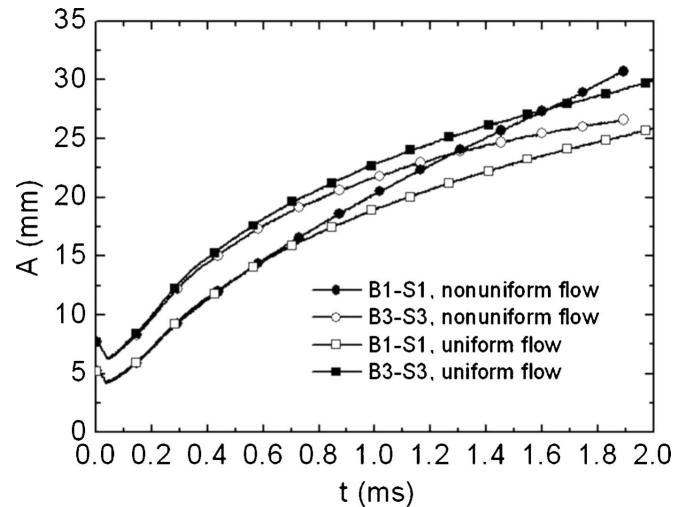


FIG. 8. Perturbation amplitude history calculations of the initial uniform and nonuniform flows in RM instability.

whole experimental process. At the same time, the differences of the initial nonuniform or uniform flow to the RM instability were analyzed and numerical and experiment results are compared to the Sadot model and Zhang-Sohn theory. This work illuminated that besides owning the identity of initial interface condition, the initial nonuniform flow would have a significant effect on the RM instability.

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